## Null Quasi-Spherical Einstein characteristic code

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[1] website: http://relativity.ise.canberra.edu.au
[2] Numerical methods for the Einstein equations in NQS coordinates, SIAM J. Sci. Comp. 22 (2000), pp917-950.

## The Null Quasi-Spherical ansatz

The NQS coordinates $(z, r, \vartheta, \varphi)$ satisfy:

- The 3 -surfaces $z=$ const. are null,
- The 2-surfaces $(z, r)=$ const. are isometric to standard 2 -spheres of radius $r$,
- The coordinates $(\vartheta, \varphi)$ are standard spherical polars

General NQS metric:

$$
d s^{2}=-2 u d z(d r+v d z)+2|r \Theta+\bar{\beta} d r+\bar{\gamma} d z|^{2}
$$

where $\Theta=\frac{1}{\sqrt{2}}(d \vartheta+\mathrm{i} \sin \vartheta d \varphi)$ and $\beta=\frac{1}{\sqrt{2}}\left(\beta^{1}-\mathrm{i} \beta^{2}\right)$
$\gamma=\frac{1}{\sqrt{2}}\left(\gamma^{1}-\mathrm{i} \gamma^{2}\right)$.

## NQS tetrad

$$
\begin{aligned}
\ell & =\frac{\partial}{\partial r}-r^{-1}\left(\bar{\beta} D_{v}-\beta D_{\bar{v}}\right)=: \mathcal{D}_{r} \\
n & =u^{-1}\left(\mathcal{D}_{z}-v \mathcal{D}_{r}\right) \\
m & =\frac{1}{\sqrt{2} r}\left(\frac{\partial}{\partial \vartheta}-\frac{i}{\sin \vartheta} \frac{\partial}{\partial \varphi}\right)
\end{aligned}
$$

The $S^{2}$ derivative operator $\partial$ (edth) acts on a spin- $s$ field

$$
\partial \eta=\frac{1}{\sqrt{2}} \sin ^{s} \vartheta\left(\frac{\partial}{\partial \vartheta}-\frac{i}{\sin \vartheta} \frac{\partial}{\partial \varphi}\right)\left(\sin ^{-s} \vartheta \eta\right)
$$

$\operatorname{div} \beta=\varnothing \bar{\beta}+\overline{\mathrm{\delta}} \beta$ is the divergence of a vector field on $S^{2}$, and $r \mathcal{D}_{r}=r \partial_{r}-\nabla_{\beta}=r \partial_{r}-(\beta \overline{\check{\delta}}+\bar{\beta} \check{\delta})$,
$r \mathcal{D}_{z}=r \partial_{z}-\nabla_{\gamma}=r \partial_{z}-(\gamma \overline{\mathrm{\delta}}+\bar{\gamma} \varnothing)$ are $S^{2}$-covariant operators.

Define the auxiliary variables $H, J, K, Q, Q^{ \pm}$in terms of the metric parameters:

$$
\begin{aligned}
H & =u^{-1}(2-\operatorname{div} \beta) \\
J & =v(2-\operatorname{div} \beta)+\operatorname{div} \gamma \\
K & =v ð \beta-\varnothing \gamma \\
Q & =r \mathcal{D}_{z} \beta-r \mathcal{D}_{r} \gamma+\gamma \\
Q^{ \pm} & =u^{-1}(Q \pm ð u)
\end{aligned}
$$

## Hypersurface Equations

The Einstein tensor components $G_{\ell \ell}, G_{\ell m}, G_{\ell n}$ and $G_{m m}$ give equations involving only derivatives tangent to the null hypersurfaces:

$$
\begin{aligned}
& r \mathcal{D}_{r} H=\left(\frac{1}{2} \operatorname{div} \beta-\frac{2|\mathrm{\partial} \beta|^{2}+r^{2} G_{\ell \ell}}{2-\operatorname{div} \beta}\right) H
\end{aligned}
$$

$$
\begin{aligned}
& r \mathcal{D}_{r} J=-(1-\operatorname{div} \beta) J+u-\frac{1}{2} u\left|Q^{+}\right|^{2}-\frac{1}{2} u \operatorname{div}\left(Q^{+}\right)-u r^{2} G_{\ell n} \\
& r \mathcal{D}_{r} K=\left(\frac{1}{2} \operatorname{div} \beta+\mathrm{i} \operatorname{curl} \beta\right) K-\frac{1}{2} \precsim \beta J+\frac{1}{2} u \precsim Q^{+}+\frac{1}{4} u\left(Q^{+}\right)^{2} \\
& +\frac{1}{2} u r^{2} G_{m m}
\end{aligned}
$$

## The NQS evolution algorithm

Begin with the primary field $\beta$ on a null hypersurface $z=z_{0}$, and progressively solve the hypersurface constraint equations, viewed as radial ODE's for the metric parameters:

1. $G_{\ell \ell}$ gives $H$, and thus $u=(2-\operatorname{div} \beta) / H$
2. $G_{\ell m}$ gives $Q^{-}$, and thus $Q$ and $Q^{+}$
3. $G_{\ell n}$ gives $J$
4. $G_{m m}$ gives $K$
5. Solving an elliptic system on $S^{2}$ determines $\gamma, v$ from $J, K$
6. Determine $\frac{\partial \beta}{\partial z}$ from $Q, \beta, \gamma$
7. Evolve $\beta$ to the next null hypersurface

Eliminating $v$ from the definitions of $J$ and $K$ gives an elliptic system for the vector field $\gamma$ restricted to the 2 -sphere $(z, r)=$ const.

$$
\partial \gamma+\frac{\partial \beta}{2-\operatorname{div} \beta} \operatorname{div} \gamma=J \frac{\partial \beta}{2-\operatorname{div} \beta}-K
$$

The right hand side is known from solving the hypersurface constraint equations, so we have an elliptic system for $\gamma$. The remaining metric parameter $v$ is then determined, by

$$
v=\frac{J-\operatorname{div} \gamma}{2-\operatorname{div} \beta}
$$

The primary field $\beta$ is evolved using $Q$ :

$$
r \frac{\partial \beta}{\partial z}=Q+r \frac{\partial \gamma}{\partial r}+\nabla_{\gamma} \beta-\nabla_{\beta} \gamma-\gamma
$$

The Bianchi II (conservation law) identity $F_{a b}{ }^{; b}=0$ for a symmetric tensor $F_{a b}$ gives equations for the components $F_{m \bar{m}}, F_{n m}, F_{n n}$ (in NP notation with $\kappa=0$ )

$$
\begin{aligned}
0= & \operatorname{Re} \rho F_{m \bar{m}}, \\
D_{\ell}\left(F_{n m}\right)= & (2 \rho+\bar{\rho}-2 \bar{\varepsilon}) F_{n m}+\sigma F_{n \bar{m}} \\
& +D_{\bar{m}} F_{m \bar{m}}+(\bar{\pi}-\tau) F_{m \bar{m}}, \\
D_{\ell}\left(F_{n n}\right)= & 2 \operatorname{Re}(\rho-2 \varepsilon) F_{n n}-\operatorname{Re} \mu F_{m \bar{m}} \\
& +D_{m} F_{n \bar{m}}+D_{\bar{m}} F_{n m}+\operatorname{Re}\left((2 \beta+2 \bar{\pi}-\tau) F_{n \bar{m})}\right) .
\end{aligned}
$$

If $\rho \neq 0$ and $F_{n m}=F_{n n}=0$ on a boundary surface transverse to the null hypersurface, then $F_{m \bar{m}}=F_{n m}=F_{n n}=0$ everywhere on the null hypersurface. Thus the constraint (subsidiary) equations are propagated by the evolution.

## Boundary (Subsidiary) Equations

The Einstein components $G_{n n}, G_{n m}$ yield the evolution $\left(\frac{\partial}{\partial z}\right)$ relations:

$$
\begin{aligned}
& r \mathcal{D}_{z}(J / u)=v^{2} r \mathcal{D}_{r}(J /(u v))+\left(\frac{1}{2} J-v\right) J / u \\
& +2 u^{-1}|K|^{2}-\nabla_{Q^{+}} v-\Delta v+u r^{2} G_{n n} \\
& r \mathcal{D}_{z} Q^{+}=\left(v r \mathcal{D}_{r}+J+\partial \bar{\gamma}-v \precsim \bar{\beta}\right) Q^{+}-K \bar{Q}^{+} \\
& +2 u^{-1} r \mathcal{D}_{r}(u \text { ठ } v)-(2+\mathrm{i} \operatorname{curl} \beta) \text { ð } v \\
& +2 \overline{\mathrm{\gamma}} K+\text { ð } J-2 u^{-1} \text { б } u J-2 u r^{2} G_{n m}
\end{aligned}
$$

These equations constrain the boundary conditions for the fields $J / u$ and $Q^{+}$. At non-boundary points they provide compatibility conditions on the $z$-derivatives.

## Free Boundary Data

- The Hypersurface Equations require boundary data (initial conditions) for $H, Q^{-}, J, K$.
- The Boundary Equations constrain the $z$-evolution of the boundary data for $J / u$ and $Q^{+}$.
- The $z$-evolution of $\beta$ is determined everwhere from $Q$.
- Consequently, the boundary data for $u, K$ are unconstrained (free).
- $u$ determines the starting sphere for the "next" null hypersurface, hence $u$ represents gauge freedom.
- $K$ describes the outgoing radiation (ingoing shear) and is free geometric data.


## Aspects of the Numerical Methods

- 8th order Runge-Kutta for the radial integration of the null hypersurface constraint ODEs, with 256 radial steps, rescaled to reach $\mathcal{I}^{+}$.
- FFT and projection to spin-weighted spherical harmonics used to minimise polar problems and to compute angular derivatives. Resolution is $L=7,15$ or 31 .
- Preconditioned conjugate gradient method to solve the elliptic system on $S^{2}$ for $\gamma$.
- 4th order Runge-Kutta for the time evolution with timestep $\Delta z=0.05$.


## Infalling radial coordinate

Use a radial grid variable $n=0, \ldots, n_{\infty}=256$ and the Schwarzschild radius function

$$
r=r(z, n)=2 M \phi^{-1}(\exp (-z / 4 M) \phi(f(n) / 2 M))
$$

where $\phi(x):=(x-1) e^{x}, x \geq 0$. Then $n=$ const. defines infalling radial curves.

Compactify $\mathcal{I}^{+}$by $n_{\infty}-n=O\left(r^{-1 / 2}\right)$, with

$$
f(n)=f_{1}(\nu) /(1-\nu)^{2}
$$

where $\nu=n / n_{\infty}, f_{1}$ monotone on $[0,1]$.


Figure 1: Evolution of $r \beta$ for $0 \leq z \leq 55$. Observe that the infalling grid tracks the dynamical evolution. $n=0$ is the past horizon $r=2 M, n=256$ is future null infinity $\mathcal{I}^{+}$.

## Kruskal-Szekeres coordinates



Figure 2: Schwarzschild spacetime in Kruskal-Szekeres coordinates.

## Numerical convergence tests

Refine code parameters:

- radial resolution $n_{\infty}=128,256,512,1024$, shows 8 -th order accuracy in radial integrations;
- angular resolution $L=7,15,31$;
- timestep $\Delta z=0.01,0.05,0.1$, shows 4 -th order accuracy in timestep;
or vary initial field strength $\beta(z=0)$ :
- weak field run_150, with $1 \%$ of the total energy as radiation
- intermediate field run_160, with $20 \%$ radiation
- strong field run_170, with $50 \%$ radiation


Figure 3: Convergence of $\beta$ with increasing radial resolution: weak field solutions with $n_{\infty}=256,512$ compared to $n_{\infty}=1024$. The error decreases by approximately a factor of $2^{8}$ on doubling the radial resolution.


Figure 4: Convergence of $\beta$ with decreasing time step: weak field solutions for $\Delta z=0.1,0.05$, compared against $\Delta z=0.025$. Where the error is not dominated by the radial discretisation error, the curves show a decrease in error which is consistent with 4th order convergence.


Figure 5: Effect of spectral resolution on constraint quantity $\left|r^{2} G_{n n}\right|_{S^{2}}$ at times $z=10,20,30,40$, for strong (top 4 curves), intermediate (middle 4 curves) and weak (bottom 4 curves) fields.

## Accuracy Conclusions

For the data studied (pure $l=2$ initial $\beta$ with Gaussian profile centered at $r=20 M$ ), the solutions are

- relatively insensitive to the timestep $\Delta z$;
- improved by increasing $n_{\infty}$;
- fundamentally limited by the spectral resolution: $L=15$ corresponds to solving the $L=10$-truncated Einstein equations.


## Geometric consistency tests

- Evaluate the constraint equations
- $G_{n n}=G_{n m}=0$ ("subsidiary" equations)
- $G_{m \bar{m}}$ ("trivial" equation).
- Test the Trautman-Bondi mass loss formula (for $\frac{d}{d z} m_{\text {Bondi }}$ ).
- Test peeling behaviour $\Psi_{k}=O\left(r^{k-5}\right)$ for the Weyl curvature components $\Psi_{k}, k=0, \ldots, 4$.


## Hawking and Bondi Mass

The Hawking mass of the $(z, r)=$ const. 2 -spheres is

$$
m_{H}(z, r)=\frac{1}{2} r\left(1-\frac{1}{8 \pi} \oint_{S^{2}} H J\right)
$$

where the integral is over the unit 2 -sphere and

$$
\oint_{S^{2}} H J=\oint_{S^{2}} \frac{1}{u}(2-\operatorname{div} \beta)(\operatorname{div} \gamma-v(2-\operatorname{div} \beta))
$$

The Bondi mass of the null hypersurface is

$$
m_{B}(z)=\lim _{r \rightarrow \infty} m_{H}(r, z)
$$

and the Trautman-Bondi mass-loss formula is

$$
\frac{d}{d z} m_{B}(z)=\frac{1}{16 \pi} \lim _{r \rightarrow \infty} \oint_{S^{2}(z, r)} H|K|^{2}
$$

## Trautman-Bondi mass decay



Figure 6: Difference between $\frac{d}{d z} m_{B}(z)$ calculated by numerical differentiation, and from the Trautman-Bondi mass-loss formula.

## Example: Peeling obstruction

Under generic asymptotic behaviour ( $r \beta$ bounded at scri), we find that $\Psi_{0}=O\left(r^{-4}\right)$, not $O\left(r^{-5}\right)$ as predicted by the peeling hypothesis.



Figure 7: Comparison of $r^{4} \Psi_{0}$ shows peeling and non-peeling behaviour

## Website demonstrations

1. $r \beta$ for run_150, $z=0 . .55-$ (a) 2 D plot with mpeg; (b) 3 D surface plot
2. spectral decay for (a) run_150 with $l=0 . .15$, (b) run_170 with $l=0 . .10$, to estimate relative accuracy by $|l=10|:|l=2|$
3. Hawking mass for run_170
4. $d m / d z$ for run_170
5. Weyl spinor $r^{5} \Psi_{0}$ for run_160, run_802
