

WMAP2D: RNPL IMPLEMENTATION OF 2+1 WAVE MAP

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1. EQUATIONS OF MOTION

Recapping, we have from [1]:

$$(1) \quad \square u^a = \epsilon u^a g^{\alpha\beta} \partial_\alpha u^b \partial_\beta u^c h_{bc}$$

$$(2) \quad u^a|_{t=0} = v^a, \quad \partial_t u^a|_{t=0} = w^a$$

where

- In case $N = S^2$, $h_{ab} = \delta_{ab}$, $\epsilon = -1$. initial data should satisfy $v^a v^b h_{ab} = 1$, $v^a w^b h_{ab} = 0$
- In case $N = H^2$, $(h_{ab}) = \text{diag}(-1, 1, 1)$, $\epsilon = +1$. initial data should satisfy $v^a v^b h_{ab} = -1$, $v^a w^b h_{ab} = 0$.

Consider the $N = S^2$ case. Adopting the usual Cartesian coordinates, (t, x, y) , we have three (component) wave fields:

$$(3) \quad u^1 := u^1(x, y, t)$$

$$(4) \quad u^2 := u^2(x, y, t)$$

$$(5) \quad u^3 := u^3(x, y, t)$$

which must satisfy

$$(6) \quad (u_1)^2 + (u_2)^2 + (u_3)^2 = 1.$$

For the purposes of finite-differencing, it is convenient to re-write (1) in first-order-in-time form. We thus introduce the ‘‘conjugate’’ variables π^a

$$(7) \quad \pi^a := u^a_{,t}$$

We now define an aciliary quantity, $s(x, y, t)$ (the ‘‘source function’’), via

$$(8) \quad s(x, y, t) := g^{\alpha\beta} \partial_\alpha u^b \partial_\beta u^c h_{bc}$$

Given that

$$(9) \quad g_{\alpha\beta} = \text{diag}(-1, 1, 1)$$

$$(10) \quad h_{ab} = \text{diag}(1, 1, 1)$$

we have

$$(11) \quad s = -(\pi^1)^2 - (\pi^2)^2 - (\pi^3)^2 + (u^1_{,x})^2 + (u^2_{,x})^2 + (u^3_{,x})^2 + (u^1_{,y})^2 + (u^2_{,y})^2 + (u^3_{,y})^2$$

With the above choices and definitions, (1) now becomes

$$(12) \quad -u^a_{,tt} + u^a_{,xx} + u^a_{,yy} = \epsilon s u^a$$

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which we then rewrite as the system of 6 PDEs for the field variables (u^a, π^a)

$$(13) \quad u^a_{,t} = \pi^a$$

$$(14) \quad \pi^a_{,t} = u^a_{,xx} + u^a_{,yy} - \epsilon s u^a$$

$$(15) \quad s = -(\pi^1)^2 - (\pi^2)^2 - (\pi^3)^2 + (u^1_{,x})^2 + (u^2_{,x})^2 + (u^3_{,x})^2 + (u^1_{,y})^2 + (u^2_{,y})^2 + (u^3_{,y})^2$$

2. IMPLEMENTATION

REFERENCES

- [1] Andersson, L; unpublished notes