PHYS 555B: Computational Physics Homework 2 (Version 5.0, homework now complete!) Due: Thursday, April 5, 2007, 9:30 AM (Report bugs etc. to choptuik@phas.ubc.ca)

Important: This assignment requires that you write three **f**77 programs which involve the solution of timedependent PDEs using finite difference approximations (FDAs).

In all cases you will ultimately be constructing programs that approximately solve initial-boundary value problems using prescribed solution domains, FDAs, initial conditions and boundary conditions. As you develop your codes to satisfy the specific homework requirements, you are free to construct and use related codes that, for example, solve the given PDE using different initial conditions than those that are to be used for the hand-in per se. In other words, do not feel overconstrained by the specific details—including command-line arguments to programs—given below, in the development of your solutions. Rather, experiment as you wish, and as needed.

That said, once you have finished with any such experimentation, please ensure that your homework does include programs with the correct names, command line arguments etc., and which function in the requested manner, including output to appropriately named .sdf files in all cases. As usual, this requirement of attention to details on your part is partly to ease in grading of the homework, but also because programming to precise specifications is a useful skill!

Note: Recall that the graphics-based programs, xvs and DV, which can greatly expedite the analysis of finite difference solutions of PDEs in 1 space dimension and time (xvs), or 2 and 3 space dimensions and time (DV), are available for your use on the lnx machines, and that data from .sdf files can be sent to those programs using the sdftoxvs and sdftodv commands, respectively. See the documentation available via the Course Related Sofware web page for additional information, and feel free to contact me should you have any questions about the use of xvs, DV, sdftoxvs, sdftodv, generation of .sdf files etc.

You should find xvs useful in the solution of the first two problems, and DV similarly useful for the third.

Problem 1:

Note: This is a perfect example of "this hurts me more than it hurts you" exercise, so please do not be intimidated or put-off by the length of the problem specification, which includes discussion of the cvtestsdf utility (used to compute convergence factors as defined in class), and other things that are not specific to this particular problem. In short, the code, wave1d.f, that you must write to solve this problem need not be very long! Further, apart from wave1d.f itself, the only additional files required to complete the question are described in section 1a) below.

Consider the 1+1 wave equation for a scalar function, $u \equiv u(x,t)$, as discussed in class,

$$u_{tt} = u_{xx} \,. \tag{1}$$

In this exercise, you will solve the above PDE as an initial-boundary value problem on the domain $0 \le x \le 1$, $0 \le t \le t_{\text{max}}$, subject to homogeneous Dirichlet boundary conditions,

$$u(0,t) = u(1,t) = 0.$$
 (2)

The issue of initial conditions will be deferred for the moment. The FDA you are to use to solve (1) is the "standard $O(h^2)$ approximation" discussed in class. That is, introduce a uniform finite difference mesh, given by

$$x_j = (j-1) \Delta x \equiv (j-1)h \quad , \quad j = 1 \dots n_x \,, \tag{3}$$

$$t^n = n \Delta t \equiv n\lambda h \quad , \quad n = 0 \dots n_t \,, \tag{4}$$

$$u_j^n \equiv u(x_j, t^n) \,. \tag{5}$$

where the number of spatial grid points, n_x , is given by $n_x = h^{-1} + 1$, and the number of time steps (minus 1), n_t , is given by

$$n_t = \frac{t_{\max}}{\Delta t} \,, \tag{6}$$

where it is assumed that t_{max} is precisely divisable by Δt .

The "standard" second order discretization of (1-2) is then given by

$$u_{j}^{n+1} = 2u_{j}^{n} - u_{j}^{n-1} + \lambda^{2} \left(u_{j+1}^{n} - 2u_{j}^{n} + u_{j-1}^{n} \right), \qquad j = 2, 3, \cdots, n_{x} - 1, \ n+1 = 2, \dots n_{t},$$
(7)
$$u_{j}^{n+1} = u_{j}^{n+1} = 0, \qquad m+1, \quad 0 = m.$$
(8)

$$u_1 = u_{n_x} = 0 \qquad n+1 = 0, \dots n_t.$$
 (8)

As was emphasized in class, in order to initialize the scheme, we need to specify u_j^0 and u_j^1 , $2 \le j \le n_x - 1$, which is equivalent (in the limit $h \to 0$) to specifying u(x,0) and $u_t(x,0)$. These in turn are the initial conditions nominally required for the solution of (1).

Your chief task in this problem is the investigation of the convergence behaviour of the finite difference approximation for two different initialization schemes, which differ in the accuracy to which the values of u_j^1 are specified.

To that end, assume that u(x,0) and $u_t(x,0)$ are known, and then consider the following two initialization schemes (both based of Taylor series expansion):

1. Second-order initialization:

$$u_{j}^{0} = u(x_{j}, 0),$$

$$u_{j}^{1} = u(x_{j}, 0) + \Delta t u_{t}(x_{j}, 0).$$
(9)

2. Third order initialization

$$u_{j}^{0} = u(x_{j}, 0),$$

$$u_{j}^{1} = u(x_{j}, 0) + \Delta t u_{t}(x_{j}, 0) + \frac{1}{2} \Delta t^{2} u_{tt}(x_{j}, 0).$$
(10)

Note that in the first initialization, the advanced values u_j^1 are computed to second order accuracy—i.e. the leading order error term is $O(\Delta t^2)$ —whereas in the second initialization, the leading order error term in the u_j^1 is $O(\Delta t^3)$.

In \sim hw2/a1 on your lnx account, create an executable wave1d (corresponding f77 source in wave1d.f) with usage

```
usage: wave1d <tmax> <lev> <olev> <lambda> <initord>
```

where the types and meanings of the various command line arguments are as follows:

- <tmax> (real*8): Final integration time, t_{max}
- <lev> (integer): Discretization level: $n_x = 2^{<lev>} + 1$, $\Delta x = h = 2^{-<lev>}$
- <olev> (integer): Output level; controls frequency of output. Must be greater than 1 and less than or equal to <lev>..sdf output is performed every 2^{<lev>-<olev>} time steps
- <lambda> (real*8): Courant number, $\lambda \equiv \Delta t / \Delta x$
- <initord> (integer): Initialization order, with valid values as follows:
 - 1. <initord> .eq. 2: Initialize u_i^1 using (9)
 - 2. <initord> .eq. 3: Initialize u_i^1 using (10)

As mentioned in the preamble, you are free to experiment with whatever initial data you please as you develop wave1d. However, the final version of wave1d *must* use the following instructor supplied functions to perform the initializations (9) and (10):

```
real*8 function u0(x)
    real*8 x
real*8 function ut0(x)
    real*8 x
real*8 function utt0(x)
    real*8 x
```

These three functions return the values u(x, 0), $u_t(x, 0)$ and $u_{tt}(x, 0)$, respectively, for a specific (yet suitably generic) choice of initial data. You should ensure that the value of x supplied to any of these routines is constrained by $0 \le x \le 1$ in all cases. The functions are defined in the f77 source file, $\sim/waveld/waveld_util.f$, which should be copied into your solution directory, then compiled and linked with your own code in waveld.f to produce the executable. As usual your directory should contain a [Mm]akefile to aid in the executable-generating process, clean up of executables and .o files, etc.

Additionally, for the purposes of testing (and in lieu of implementation of an independent residual evaluator), wave1d_util.f contains an additional function

```
real*8 function uexact(x,t)
  real*8 x, t
```

that, for the initial data defined via u0 and ut0 only, and for $0 \le t \le 0.25$, will return a good approximation to the exact solution, u(x, t).

You will probably find it most convenient to use the Fortran callable routine, **xvs** (not to be confused with the related **xvs** visualization utility),

subroutine xvs(nam	e,time,x,y,nx)	
character*(*)	name	! dataset name
real*8	time	! dataset time (scalar)
integer	nx	! length of dataset
real*8	x(nx), y(nx)	! x, y values of dataset (vectors)

to generate the required .sdf output, which, for the final version of wave1d, is the single grid function u_j^n , at discrete times t^n defined by <tmax>, <lambda>, <lev> and <olev>. Observe that executables that invoke xvs must link to some additional libraries. Specifically,

-lsvs -lbbhutil -lsv

must be included in the linking command that creates wave1d. Note that on the lnx machines the environment variable LIBXVS should evaluate to the above library specification string, enabling you to use \$(LIBXVS) in your [Mm]akefile to link against the appropriate archives.

For any invocation of wave1d, the name of the .sdf file generated should be of the form

u-<initord>-<lev>.sdf

Thus, the invocation

% wave1d 0.5 9 8 0.5 2

should generate

u-2-9.sdf

while

% wave1d 0.5 11 8 0.5 3

should generate

u-3-11.sdf

Files with such names can be easily produced using the utility character function, itoc, that is defined in the libp410f library, and that can be used as illustrated by the following code fragment:

```
character*2 itoc
real*8 x(10000), u(10000)
real*8 t
integer lev, initord, nx
.
.
.
.
initord = 3
lev = 9
call xvs('u-'//itoc(initord)//'-'//itoc(lev),t,x,u,nx)
.
.
.
.
```

The call to xvs in the above will result in the creation of u-3-9.sdf. Note how itoc is declared, i.e. as type character*2, so that, irrespective of how many digits there are in the integer supplied as an argument to itoc, a length-2 character string will be returned, right-padded with spaces as necessary. Also note that in generating a filename from its first argument, xvs discards any characters, including white space, that are not alphanumeric, underscore, or minus sign.

Be cautious in your handling of command line arguments, the derivation of quantities, such as n_t , that depend the value of these arguments, and the output of data via calls to xvs at discrete time intervals controlled by <lev> and <olev>. In particular, a series of invocations such as

% wave1d 1.0 8 8 0.5 3 % wave1d 1.0 9 8 0.5 3 % wave1d 1.0 10 8 0.5 3

should result in three .sdf files containing the same number of datasets, defined at the name set of discrete times, t^n , including the initial and final times, t = 0.0 and t = 1.0, respectively.

The cvtestsdf utility

Recall from our in-class discussion of the convergence of finite difference approximations of time-dependent PDEs, that given finite difference solutions generated from the same initial conditions, but using discretization scales in a 1: 2: 4 ratio, we can define a convergence factor, Q(t)

$$Q(t^{n}) \equiv \frac{\|u^{4h} - u^{2h}\|_{2}(t^{n})}{\|u^{2h} - u^{h}\|_{2}(t^{n})}$$
(11)

where $\|\cdot\|$ is the discrete ℓ_2 norm, the subtractions between grid functions are to be understood to be made on the set of grid points common between the two discrete domains, and the 3 grid functions must all be defined at the same discrete set of times, t^n . In the limit $h \to 0$, the convergence factor, Q(t), should asymptote to 2^p for a *p*-th order accurate scheme.

Given three .sdf files, each of which contains one of u^{4h} , u^{2h} or u^h , cvtestsdf computes $Q(t^n)$ as defined by (11) and then outputs t^n and $Q(t^n)$ to standard output, two numbers per line. You will use this utility to complete the current problem, and will likely find it convenient in investigating the convergence of the codes that you will write in the other two parts of the homework.

You can see an example of how cvtestsdf works, and what sort of output it produces, via the files in ~phys410/cvtestsdf on the lnx machines. Here's a session trace which shows the "demo" being executed as matt@lnx1.physics.ubc.ca.

```
% mkdir /tmp/demo
% cd /tmp/demo
\% cp -a ~phys410/cvtestsdf .
% cd cvtestsdf
# Generate 'cvtestsdf' usage message
% cvtestsdf
usage: cvtestsdf <file 1> <file 2> <file 3> [<dstem> <base level>]
       Computes and outputs to standard output the time, t, and
       the three-level convergence factor, Q(t), defined by
              ||u^4h - u^2h||_2 (t)
       Q(t) = ------
              ||u^2h - u^h||_2 (t)
       As h \rightarrow 0, Q(t) should asymptote to 2<sup>p</sup> for a pth order accurate scheme.
       Specify .sdf files containing single grid function (u) from coarsest to
       finest resolution. Grid resolutions must be in the ratio 4:2:1.
       All files must contain grid functions defined at
       the same output times.
       Supply <dstem> for pointwise-difference output to
       2 RNPL-style .sdf files with names of the form
          <dstem><l><l+1>.sdf
          <dstem><l+1><l+2>.sdf
       where <l> defaults to 0, but will be set to <base level>
       if that argument is supplied.
# Run 'wave1d' at levels 8, 9, 10, and with 'intord=3' ...
% wave1d 0.5 8 8 0.5 3
% wave1d 0.5 9 8 0.5 3
% wave1d 0.5 10 8 0.5 3
% ls *sdf
u-3-10.sdf u-3-8.sdf u-3-9.sdf
# ... and compute resulting convergence factor using 'cvtestsdf'
% cvtestsdf u-3-8 u-3-9 u-3-10
0 0
0.00195312 3.92482
0.00390625 3.90415
0.00585938 3.88856
0.0078125 3.87815
```

0.492188 3.94048 0.494141 3.95249 0.496094 3.96272 0.498047 3.9714 0.5 3.97876

Note that at $t^n = 0$, cvtestsdf computes $Q(t^n) = 0$. You will frequently see this behaviour, which should be viewed as anomalous: because a closed-form prescription of the initial data is used by wave1d, equation (11) for Q(t) evaluates to 0/0, which cvtestsdf arbitrarily replaces with 0.

Problem 1a) Once you are satisfied that your version of wave1d has been implemented correctly, according to the specifications above, copy the script wave1d-script from \sim /phys410/cvtestsdf to the solution directory for this question, and then execute it. If you *have* implemented wave1d correctly, this will run calculations for both second and third order initializations, and for discretization levels 8 through 12 respectively. In addition, cvtestsdf will be invoked to compute $Q(t^n)$ for levels 8, 9, 10, levels 9, 10, 11 and levels 10, 11, 12, and for both orders of initialization. The output from the six invocations of cvtestsdf will be captured in files

```
cvt-2-10-11-12 cvt-2-8-9-10 cvt-2-9-10-11 cvt-3-10-11-12 cvt-3-8-9-10 cvt-3-9-10-11
```

where the filename-encoding of the initialization order and the discretization levels used in the computation of $Q(t^n)$ should be self-explanatory.

Using the above 6 files make a *single* postscript file, cvt23.ps, which shows $Q(t^n)$ versus t^n from all 6 invocations of cvtestsdf on a single plot. Your plot should use a *y*-range (i.e. range of $Q(t^n)$) of 1.5 to 4.5. Briefly summarize what you conclude about the convergence of your code for the two different values of intord in a README file in the solution directory.

I will also test your implementation of wave1d using invocations other than those performed by wave1d-script.

Problem 2: The 1-d Time-dependent Schrodinger equation

Note: This problem requires that you use f77's built in facilities for handling complex quantities. See the code democomplex.f, available via the "Miscellaneous" section of the Course Related Sotware web page for a brief demonstration of the use of the complex*16 data type in f77, including basic arithmetic operations, as well as some of the more important intrinsic (built-in) functions that are available to manipulate complex values.

Consider the non-dimensionalized form of the 1-d time-dependent Schrödinger equation for the complex (wave) function, $\psi \equiv \psi(t, x)$, as discussed in class,

$$i\psi_t = -\psi_{xx} + V(x)\psi, \qquad (12)$$

where V(x) is a specified potential function.

In this exercise, you will solve the above PDE on the domain $0 \le x \le 1$, $0 \le t \le t_{\text{max}}$, subject to homogeneous Dirichlet boundary conditions,

$$\psi(0,t) = \psi(1,t) = 0, \qquad (13)$$

corresponding to infinite potential barriers at x = 0 and x = 1.

Again, the issue of initial conditions will be deferred for the time being.

Equation (12) is to be solved using the $O(h^2)$ Crank-Nicholson approximation also discussed in class. Introduce the exact same finite difference mesh used in the previous problem:

$$x_j = (j-1) \Delta x \equiv (j-1)h \quad , \quad j = 1 \dots n_x \,, \tag{14}$$

$$t^{n} = n \Delta t \equiv n \lambda h \quad , \quad n = 0 \dots n_{t} \,, \tag{15}$$

$$\psi_j^n \equiv \psi(x_j, t^n). \tag{16}$$

where n_x and n_t are defined as previously.

Define the standard $O(h^2)$ approximation to the second spatial derivative via the difference operator, D_{xx} :

$$D_{xx} \psi_j^n \equiv \frac{\psi_{j+1}^n - 2\psi_j^n + \psi_{j-1}^n}{\triangle x^2}.$$
 (17)

The Crank-Nicholson differencing of (12-13) is then given by

$$i\frac{\psi_{j}^{n+1} - \psi_{j}^{n}}{\Delta t} = -\frac{1}{2}D_{xx}\left(\psi_{j}^{n+1} + \psi_{j}^{n}\right) + \frac{1}{2}V_{j}\left(\psi_{j}^{n+1} + \psi_{j}^{n}\right)$$
(18)

$$\begin{aligned} j &= 2, 3, \cdots, n_x - 1, \quad n+1 = 1, \dots n_t , \\ \psi_1^{n+1} &= \psi_{n_x}^{n+1} = 0 \qquad n+1 = 1, \dots n_t . \end{aligned}$$
 (19)

Note that (18-19) constitute a complex tridiagonal linear system for the n_x advanced time unknowns, ψ_j^{n+1} . Wave function normalization and auxiliary quantities

Recall the physical interpretation of

$$\left|\psi(x,t)\right|^2 dx \equiv \psi(x,t)\psi^*(x,t)\,dx\,,\tag{20}$$

as being the probability of finding the particle described by the Schrödinger equation (12) in the interval (x, x + dx) at time t. Thus, $\psi(t, x)$ is to be normalized so that

$$\int_{0}^{1} |\psi(x,t)|^{2} dx = 1.$$
(21)

Note that if (21) is satisfied at the initial time, t = 0, then evolution of ψ via (12) guarantees that the wave function remains normalized at future and past times. Of course, this a statement concerning the *continuum* solution, and can not necessarily be expected to hold precisely in the discrete case.

The specific types of initial data (and in one instance, the exact solution) that you are to implement, as described below, will generally produce unnormalized wave functions. For your convenience, the source file ~phys410/util/sch1d/sch1d_util.f defines a routine, psi_normalize

```
subroutine psi_normalize(psi,x,nx)
implicit none
integer nx
complex*16 psi(nx)
real*8 x(nx)
```

which will unit-normalize an arbitrary discrete wave function using an $O(h^2)$ approximation to (21). Specifically, the complex*16 grid function psi is both an input and output argument. On input, it should contain values corresponding to an arbitrary unnormalized wave function: on output, it will then contain values that are unit-normalized with respect to the aforementioned second order approximation to (21).

As is frequently the case in computational physics, the fundamental solution, $\psi(x, t)$, is not the most convenient quantity for interpretation of results, visualization etc. (although the discrete solution ψ_j^n is certainly the quantity on which one should focus until convergence of the implementation has been established). In the current case, "auxiliary" or "derived" quantities that are of specific interest include: $|\psi(x,t)|^2$, the cumulative probability function, P(x,t), defined via

$$P(x,t) \equiv \int_0^x \left|\psi(\tilde{x},t)\right|^2 \, d\tilde{x} \,, \tag{22}$$

as well as the time expectation value, $\langle P(x,t) \rangle$ of P(x,t):

$$\langle P(x,t)\rangle \equiv \frac{\int_0^t P(x,\tilde{t})d\tilde{t}}{\int_0^t d\tilde{t}}.$$
(23)

Note that the spatial derivative of $\langle P(x,t) \rangle$ is the time expectation value of the probability distribution:

$$\frac{\partial}{\partial x} \left\langle P(x,t) \right\rangle = \left\langle \left| \psi(x,t) \right|^2 \right\rangle, \tag{24}$$

and is also of interest for the purposes of analysis of the numerical results.

As a further aid to the development of your programs to solve (18-19), the following routine (as well as supporting code) is also defined in the source file ~phys410/util/sch1d_sch1d_util.f:

In this routine, the grid function $psi(\psi_j^n)$ is the primary input—from it, the routine computes auxiliary grid functions as follows:

psire
$$\equiv \operatorname{Re}\left(\psi_{j}^{n}\right)$$
, (25)

$$psiim \equiv Im\left(\psi_j^n\right), \qquad (26)$$

$$psimodsq \equiv \left|\psi_{j}^{n}\right|^{2}, \qquad (27)$$

$$pcum \equiv P_{i}^{n}, \qquad (28)$$

$$pcumtexp \equiv \langle P \rangle_j^n.$$
(29)

Note that **x** is the vector of spatial coordinates, while **t** and **dt** are the corresponding integration time, t^n , and time step, Δt , respectively. Further note that pcumtexp is both an input and output argument. On input, and for any discrete time other than the initial one (i.e. for $t^n \neq 0$), pcumtexp should contain $\langle P \rangle_j^{n-1}$ —on output pcumtexp will contain $\langle P \rangle_j^n$. When psi_aux is invoked at the initial time (i.e. with t = 0), pcumtexp will be initialized to P_j^0 . Finally, as can be seen from inspection of the source code for psi_aux, the computations of P_j^n and $\langle P \rangle_j^n$ are performed using $O(h^2)$ approximations, consistent with the truncation error of the basic scheme (18-19).

To complete this problem, you are to write two separate codes, each of which solves (18-19) for a particular combination of initial data type and potential. Specifically, the two codes will treat the following cases

1. Evolution of an eigenstate for vanishing potential (free particle in a box)

Here the potential is given by

$$V(x) = 0 \qquad 0 < x < 1, \tag{30}$$

$$V(x) = \infty \qquad x = 0, \ x = 1,$$
 (31)

and the (exact) eigenstates are given by

$$\psi(x,t) = \exp\left(-i\left(m\pi\right)^2 t\right)\sin(m\pi x) \quad m = 1, 2, \cdots$$
(32)

where m is the "principal quantum number". (Kudos, Robert Kehoe, 2007, for catching the $-i \rightarrow i$ sign error. Clearly the instructor didn't test his exact solution implementation except at the initial time!)

Important note: As intimated previously, the initial data prescriptions (32) and (37) define *unnor-malized* wave functions. Thus, each time you use one of these expressions (in a routine that computes the exact solution, e.g.), then you must normalize the function. Again, this can be done with a single call to the instructor-supplied routine, psi_normalize.

For specfied m (which will be treated as an adjustable parameter), the initial data is to be given by (32) evaluated at t = 0, that is

$$\psi(x,0) = \sin(m\pi x). \tag{33}$$

(Note that the initial wave function is purely real.)

2. Evolution of a gaussian wave-packet, possibly boosted, with a single square well, or square barrier potential

In this case the potential is given by three parameters, x_{\min} , x_{\max} and V_0 , as follows

$$V(x) = V_0 \qquad x_{\min} \le x \le x_{\max} , \qquad (34)$$

$$V(x) = \infty \qquad x = 0, \ x = 1,$$
 (35)

$$V(x) = 0 \qquad \text{otherwise.} \tag{36}$$

For V_0 positive (negative), this corresponds to a single square barrier (well) of height (depth) $|V_0|$ spanning the interval $x_{\min} \leq x \leq x_{\max}$. The initial data is a gaussian wave packet, possibly boosted (i.e. given some linear momentum), and is also a function of three parameters x_c , x_w (the center and width of the packet) and p (the momentum). Specifically

$$\psi(x,0) = \exp\left(ipx\right)\exp\left(-\left(\left(x-x_c\right)/x_w\right)^2\right).$$
(37)

In the solution directory for this assignment, ~/hw2/a2, you are to create executables sch1d_eig and sch1d_square (with corresponding source files containing the main programs sch1d_eig.f and sch1d_square.f, respectively) that have usages as follows

1. sch1d_eig

usage: sch1d_eig <tmax> <lev> <olev> <lambda> <m>

where the types and meanings of the various command line arguments are as follows

- <tmax> (real*8): Final integration time, t_{max}
- <lev> (integer): Discretization level: $n_x = 2^{<lev>} + 1$, $\Delta x = h = 2^{-<lev>}$
- <olev> (integer): Output level; controls frequency of output. Must be greater than 1 and less than or equal to <lev>..sdf output is performed every 2^{<lev>-<olev>} time steps
- <lambda> (real*8): Courant number, $\lambda \equiv \Delta t / \Delta x$
- <m> (integer): Principal quantum number. Must be positive definite.
- 2. sch1d_square

```
usage: sch1d_square <tmax> <lev> <olev> <lambda> <xc> <xw>  <xmin> <xmax> <VO>
```

where the types and meanings of the various command line arguments are as follows

- <tmax> (real*8): As above.
- <lev> (integer): As above.
- <olev> (integer): As above.
- <lambda> (real*8): As above.
- <xc> (real*8): Center, x_c , of initial gaussian pulse.
- <xw> (real*8): Width, x_w , of initial gaussian pulse.
- (real*8): Momentum, p, of initial pulse.
- <xmin> (real*8): Spatial location, x_{min} , of start of potential barrier/well.
- <xmax> (real*8): Spatial location, x_{max} , of end of potential barrier/well.
- <V0> (real*8): Value, V₀, of potential in barrier/well.

The two programs that you construct may (should?) share considerable code, and must adhere to the following:

1. Solution of the FDA

The Crank-Nicholson FDA for the Schrödinger equation is to be solved using the LAPACK routine ZGTSV, which solves a complex*16 tridiagonal linear system. The calling sequence for ZGTSV is precisely the same as for DGTSV, except that ZGTSV expects a complex*16 array everywhere that DGTSV expects a real*8 one:

```
SUBROUTINE ZGTSV( N, NRHS, DL, D, DU, B, LDB, INFO )
*
  -- LAPACK routine (version 3.0) --
*
     Univ. of Tennessee, Univ. of California Berkeley, NAG Ltd.,
*
      Courant Institute, Argonne National Lab, and Rice University
      September 30, 1994
      .. Scalar Arguments ..
      INTEGER
                         INFO, LDB, N, NRHS
      .. Array Arguments ..
*
                         B( LDB, * ), D( * ), DL( * ), DU( * )
      COMPLEX*16
      . .
```

2. Scaled independent residual evaluation

Scaled independent residuals, r_j^{n+1} , are to be computed and output (see below) using the following first order (i.e. O(h) truncation error) discretization of (12)

$$r_{j}^{n+1} \equiv 2^{\ell} \left| i \frac{\psi_{j}^{n+1} - \psi_{j}^{n}}{\Delta t} + D_{xx} \psi_{j}^{n+1} - V_{j} \psi_{j}^{n+1} \right|,$$
(38)

$$j = 2, 3, \dots, n_x - 1, n + 1 = 2, \dots n_t,$$

$$r_{1}^{n+1} = 0, (39)$$

$$r_{n_x}^{n+1} = 0. (40)$$

Note the prefactor of 2^{ℓ} in the definition of r_j^{n+1} , where ℓ is the discretization level (i.e. $\ell = \langle \texttt{lev} \rangle$) Since the independent discretization is O(h) accurate, multiplication of the bare residual by 2^{ℓ} should produce a quantity that is roughly discretization-level-independent, in the limit $h \to 0$. Observe that the independent residual is undefined at the initial time, and thus should not be computed or output for n = 0.

3. Incorporation of instructor-supplied utility routines

Make a copy of ~phys410/util/sch1d/sch1d_util.f in your solution directory, and incorporate the code contained therein into your executables so that the routines psi_normalize and psi_aux can be used in your implementations, as described above.

4. Program output: .sdf files

The following six *real-valued* grid functions should be output to .sdf files using calls to xvs, and at a frequency controlled by the command-line arguments lev and olev, as for the wave1d problem:

- (a) Re $\left(\psi_{j}^{n}\right)$: Real part of wave function
- (b) Im $\left(\psi_{j}^{n}\right)$: Imaginary part of wave function
- (c) $|\psi_i^n|^2$: Squared-modulus of wave function
- (d) P_i^n : Cumulative probability distribution
- (e) $\langle P \rangle_{i}^{n}$: Time expectation value of cumulative prob. distribution
- (f) r_i^n : Independent residual

5. Names of .sdf files

The type of evolution, the discretization level, <lev>, and, in the case of sch1d_eig, the principal quantum number <m>, should be encoded in the .sdf filenames as follows:

(a) *Program* sch1d_eig

.sdf files should be named as follows

```
psire-eig-<m>-<lev>.sdf
psiim-eig-<m>-<lev>.sdf
psimodsq-eig-<m>-<lev>.sdf
pcum-eig-<m>-<lev>.sdf
pcumtexp-eig-<m>-<lev>.sdf
irmod-eig-<m>-<lev>.sdf
```

corresponding to $\operatorname{Re}\left(\psi_{j}^{n}\right)$, $\operatorname{Im}\left(\psi_{j}^{n}\right)$, $|\psi_{j}^{n}|$, P_{j}^{n} , $\langle P \rangle_{j}^{n}$ and r_{j}^{n} , respectively. For example, the invocation

% sch1d_eig 0.1 10 6 0.05 3

should produce the files

```
psire-eig-3-10.sdf
psiim-eig-3-10.sdf
psimodsq-eig-3-10.sdf
pcum-eig-3-10.sdf
pcumtexp-eig-3-10.sdf
irmod-eig-3-10.sdf
```

(b) *Program* sch1d_square

.sdf files should be named as follows

```
psire-square-<lev>.sdf
psimodsq-square-<lev>.sdf
pcum-square-<lev>.sdf
pcumtexp-square-<lev>.sdf
irmod-square-<lev>.sdf
```

corresponding to $\operatorname{Re}\left(\psi_{j}^{n}\right)$, $\operatorname{Im}\left(\psi_{j}^{n}\right)$, $|\psi_{j}^{n}|, P_{j}^{n}$, $\langle P \rangle_{j}^{n}$ and r_{j}^{n} , respectively. For example, the invocation

% sch1d_square 0.1 11 5 0.05 0.5 0.075 0.0 0.6 0.8 -1000

should produce the files

```
psire-square-10.sdf
psiim-square-10.sdf
psimodsq-square-10.sdf
pcum-square-10.sdf
pcumtexp-square-10.sdf
irmod-square-10.sdf
```

Note that the character function itoc, described in the first problem, can be used here as well to encode <lev> and <m> into the .sdf names.

Code testing

It is up to you to convergence test your codes using one or more of

- 1. xvs's convergence test facility
- 2. cvtestsdf
- 3. independent residual study
- 4. the exact solution, where available

in order to verify that your implementations are correct.

Problem 2a)

Once you are satisfied that your implementation of schld_square is correct, perform 4 runs of the program with $\langle VO \rangle = -10000.0, -12000.0, -13000.0$ and -15750.0, respectively, and with the values of all other command-line arguments fixed as follows: $\langle tmax \rangle = 0.05$, $\langle lev \rangle = 12$, $\langle olev \rangle = 8$, $\langle lambda \rangle = 0.05$, $\langle xc \rangle = 0.25$, $\langle xw \rangle = 0.075$, $\langle p \rangle = 5.0$, $\langle xmin \rangle = 0.60$ and $\langle xmax \rangle = 0.80$.

Use the results from these runs to prepare 4 plots that graph $\langle |\psi(x, 0.05)|^2 \rangle$ versus x, for the 4 different values of <V0>; i.e. the plots are to display the time expectation value of the probability distribution at the final integration time, t = 0.05. Your plots should be saved in postscript files named V0-10000.ps, V0-12000.ps, V0-13000.ps and V0-15750.ps, respectively.

Provide some brief comments concerning what you observe in, and deduce from, these plots in a **README** file in the solution directory.

Course software usage hints:

1. You can use the xvs visualization utility to (a) compute

$$\left\langle \left| \psi(x,t) \right|^2 \right\rangle = \frac{\partial}{\partial x} \left\langle P(x,t) \right\rangle$$
(41)

from $\langle P(x,t)\rangle$, via numerical differentiation, and, (b) then save $\langle |\psi(x,t)|^2 \rangle$ in an .sdf file.

2. You can use the sdfdump utility in conjunction with the instructor supplied script, nth, to generate ASCII data suitable for plotting with gnuplot or other plotting packages. Specifically, if the file f.sdf, storing the grid function, f_j^n , contains (for example), 15 datasets, then the pipeline

sdfdump -i 15 f.sdf | nth 2 3

will produce on standard output

$$\begin{array}{cccc} x_1 & & f_1^{15} \\ x_2 & & f_2^{15} \\ & \cdot & \\ & x_{n_x} & & f_{n_x}^{15} \end{array}$$

Both sdfdump and nth are available on the lnx machines. Contact the instructor should you wish to install these utilities on your own system(s) and/or should you have any questions about their use.

Problem 3: Solution of the 2D diffusion equation using the ADI FDA.

Consider the non-dimensionalized 2+1 diffusion equation for the scalar function $u \equiv u(x, y, t)$ as discussed in class,

$$u_t = u_{xx} + u_{yy}, \tag{42}$$

with unit-square domain

$$0 \le x, y \le 1, \tag{43}$$

subject to the initial conditions

$$u(x, y, 0) = u_0(x, y),$$
(44)

where $u_0(x, y)$ is a specified function, and boundary conditions

$$u(0, y, t) = u(1, y, t) = u(x, 0, t) = u(x, 1, t) = 0.$$
(45)

Introduce a standard, uniform finite difference mesh:

$$x_i = (i-1) \Delta x \equiv (i-1)h \quad , \quad i = 1 \dots n_x \tag{46}$$

$$y_j = (j-1) \bigtriangleup y \equiv (j-1)h \quad , \quad j = 1 \dots n_y \tag{47}$$

$$t^n = n \,\triangle t \equiv n \lambda h \quad , \quad n = 0 \dots n_t \tag{48}$$

$$u_{ij}^{n} \equiv u(x_i, y_j, t^n) \tag{49}$$

Note that $n_x = n_y = h^{-1} + 1$, and that hereafter we will denote either of n_x or n_y by n_s .

Define the usual centred, $O(h^2)$ difference operators, D_{xx} and D_{yy} , that approximate the continuum operators, ∂_{xx} and ∂_{yy} , respectively:

$$D_{xx}u_{i,j}^{n} \equiv \frac{u_{i+1,j}^{n} - 2u_{i,j}^{n} + u_{i-1,j}^{n}}{\Delta x^{2}},$$
(50)

$$D_{yy}u_{i,j}^{n} \equiv \frac{u_{i,j+1}^{n} - 2u_{i,j}^{n} + u_{i,j-1}^{n}}{\Delta y^{2}}.$$
(51)

Define the Crank Nicholson approximation to (42-45) as follows:

Discretization of interior PDE

$$\frac{u_{i,j}^{n+1} - u_{i,j}^{n}}{\triangle t} = \frac{1}{2} \left(D_{xx} + D_{yy} \right) \left(u_{i,j}^{n+1} + u_{i,j}^{n} \right) \quad , \quad i, j = 2 \dots n_s - 1 \quad , \quad n = 0, 1, \dots n_t - 1 \,. \tag{52}$$

Discretization of initial conditions

$$u_{i,j}^{0} = u_0(x_i, y_j, t^0) \equiv u_0(x_i, y_j) \quad , \quad i, j = 2 \dots n_s - 1 \,.$$
(53)

Discretization of boundary conditions

$$u_{1,j}^{n} = u_{n_{s},j}^{n} = 0 \quad , \quad j = 1 \dots n_{s} \; , \; n = 0 \dots n_{t} \; , \tag{54}$$

$$u_{i,1}^{n} = u_{i,n_{s}}^{n} = 0 \quad , \quad i = 1 \dots n_{s} \; , \; n = 0 \dots n_{t} \, .$$
(55)

Again, the specific form of the discrete initial and boundary conditions ensures (discrete) compatibility of the initial conditions with the boundary conditions, and the usual caveat concerning the need to ensure that effects due to small numerical inconsistencies are sub-truncation error, holds.

As discussed in class, the ADI approximation to (42), written in the form

$$\left(1 - \frac{1}{2} \bigtriangleup t D_{xx}\right) \left(1 - \frac{1}{2} \bigtriangleup t D_{yy}\right) u_{i,j}^{n+1} = \left(1 + \frac{1}{2} \bigtriangleup t D_{xx}\right) \left(1 + \frac{1}{2} \bigtriangleup t D_{yy}\right) u_{i,j}^{n},$$
(56)

has the same order of truncation error (i.e. $O(h^2)$) as the Crank-Nicholson (CN) approximation (52), where here and hereafter the discrete initial and boundary conditions are unchanged from the CN approximation, as above.

Further, using an intermediary grid function, $u_{i,i}^{\star}$ the solution of (56) can be split into two stages, as follows:

$$\left(1 - \frac{1}{2} \Delta t D_{xx}\right) u_{i,j}^{\star} = \left(1 + \frac{1}{2} \Delta t D_{yy}\right) u_{i,j}^{n} , \quad i, j = 2 \dots n_s - 1 \quad , \quad n = 0 \dots n_t , \tag{57}$$

$$\left(1 - \frac{1}{2} \Delta t D_{yy}\right) u_{i,j}^{n+1} = \left(1 + \frac{1}{2} \Delta t D_{xx}\right) u_{i,j}^{\star} , \quad i, j = 2 \dots n_s - 1 \quad , \quad n = 0 \dots n_t \,. \tag{58}$$

Equations (57-58) together with the initial conditions (53) and boundary conditions (54-55) define the complete ADI FDA.

In the solution directory for this assignment, create the subdirectory a3, which is to contain an implementation of the ADI equations for the 2D diffusion equation, as described above. Specifically, you are to create an executable, diff2dadi, with one or more corresponding f77 files, including diff2dadi.f, which should contain the main program. diff2dadi has usage

usage: diff2dadi <tmax> <lev> <olev> <lambda>

where the types and meanings of the various command-line arguments are as follows:

- <tmax> (real*8): Final integration time, t_{max}
- <lev> (integer): Discretization level: $n_x = n_y = n_s = 2^{<lev>} + 1$, $\Delta x = \Delta y = h = 2^{-<lev>}$
- <olev> (integer): Output level; controls frequency of output. Must be greater than 1 and less than or equal to <lev>..sdf output (see below) is performed every 2^{<lev>-<olev>} time steps
- <lambda> (real*8): Courant number, $\lambda \equiv \Delta t / \Delta x$

Your program should adhere to the following:

• Solution of the FDA

Implement the ADI equations precisely as defined above, and use the LAPACK tridiagonal solver DGTSV to solve all tridiagonal systems that arise in the ADI solution.

• Program output: .sdf files

Periodically, with a frequency controlled by the command-line arguments <lev> and <olev>, as in previous questions, your program should use one of the following routines to output the computed solution to an .sdf file named u-<lev>.sdf, where <lev> is to replaced with the actual integer value of <lev> that is supplied on the command line:

```
subroutine gft_out_bbox(name,time,shape,rank,bbox,data)
```

character*(*)	name	!	dataset name
real*8	time	!	dataset time
integer	shape(2)	!	shape of data: [nx ny]
integer	rank	!	dataset rank (number of dimensions), 2 in this instance
real*8	bbox(4)	!	bounding box for data: [xmin xmax ymin ymax]
real*8	data(shap	be	(1),shape(2)) ! 2D dataset

```
subroutine gft_out_brief(name,time,shape,rank,data)
```

character*(*)	name	!	dataset name
real*8	time	!	dataset time
integer	shape(2)	!	shape of data: [nx ny]
integer	rank	!	dataset rank (number of dimensions), 2 in this instance
real*8	data(shap	be	(1),shape(2)) ! 2D dataset

If you use the gft_out_brief routine, you should call gft_out_set_bbox

subroutine	gft_out_set_bbox(bb	bo	ox,ran	k)								
integer	rank !	!	rank o	of	datas	sets	to	be	output	5		
real*8	bbox(*) !	!	bound	ing	box	for	dat	a:	[xmin	xmax	ymin	ymax]

before any calls to gft_out_brief, in order to set the bounding box to [0.0 1.0 0.0 1.0]. (The default for 2D data is to assume a domain defined by the bounding box [-1.0 1.0 -1.0 1.0].)

As usual, let the instructor know immediately should you have difficulty with these routines, or if you have questions about their use and/or visualization of the contents of 2D .sdf files with the DV application that was demoed over mid-term break.

• Initial data

As you develop your program, you are free to use initial data of your own choosing. However, the final version of your code should "hard-code" the following specific initial conditions

$$u(x, y, 0) = u_0(x, y) = \exp\left(-\left(\left(\frac{x - 0.6}{0.05}\right)^2 + \left(\frac{y - 0.7}{0.10}\right)^2\right)\right).$$
(59)

Note, however, that the above expression is to be used only for the *interior* grid points at t = 0. The boundary values at the initial time should be set to 0.0 per the discrete boundary conditions (54-55).

• Independent residual evaluation and output

In this instance there is, of course, a very natural independent residual with which one can test the implementation of the ADI scheme—namely that provided by the Crank-Nicholson discretization (52) itself. Specifically, momentarily denoting the solution of the ADI FDA by \tilde{u}_j^n , then the Crank-Nicholson residual, $r_{i,j}^{n+1/2}$, is given by

$$r_{i,j}^{n+1/2} \equiv \frac{\tilde{u}_{i,j}^{n+1} - \tilde{u}_{i,j}^{n}}{\Delta t} - \left[\frac{1}{2} \left(D_{xx} + D_{yy}\right) \left(\tilde{u}_{i,j}^{n+1} + \tilde{u}_{i,j}^{n}\right)\right].$$
(60)

As discussed in class (in the general context of independent residual evaluation), viewing r as a function defined on the continuum, we can expect the following asymptotic behaviour:

$$\lim_{h \to 0} r(t, x; h) = h^2 r_2(t, x) + \text{higher order}, \qquad (61)$$

where r_2 is some *h*-independent function.

Important note: Observe that the residual (60) is naturally defined at discrete times $t^{n+1/2} \equiv t^n + \Delta t/2, n = 0, \ldots n_t - 1$. From the point of view of the usual sort of convergence tests discussed in the course, one consequence of this fact is that it will be generally impossible to *directly* compare the residuals computed at different levels, ℓ , of discretization, with corresponding mesh spacings $h_{\ell} = h_{\ell-1}/2$. That is, although the discrete times, $t^n_{\ell-1}$, on a coarse grid will be a subset of the fine grid times, t^n_{ℓ} , none of the values $t^{n+1/2}_{\ell-1}$, from the coarse grid will correspond to the "half time step" values, $t^{n+1/2}_{\ell}$ on the fine grid. Thus, a direct comparison of independent residuals computed on different levels would require interpolation in time of the residuals, and would constitute an overly cumbersome procedure, given the purpose of the residual evaluation.

Given this observation, consider computing the spatial ℓ_2 norm (RMS value), $||r||_2$, of r at each discrete time step. Clearly, $||r||_2$ should also be an $O(h^2)$ quantity, so that if we compute a "level-scaled" residual norm, $\hat{r}(t; h)$, defined by

$$\hat{r}\left(t^{n+1/2};h_{\ell}\right) \equiv 4^{\ell} \left\|r_{i,j}^{n+1/2}\right\|_{2},$$
(62)

then we should find that $\hat{r}(t, h)$ is an approximately *h*-independent function. Further, it is extremely improbable that ||r|| can be $O(h^2)$ without (61) being satisfied, so that we can essentially view the constancy of \hat{r} , as $h \to 0$, as a *sufficient* as well as *necessary* condition for the implementation of the ADI FDA to be correct.

Thus, for time steps, $n = 0 \dots n_t - 1$, your program should compute the scaled residual norm (62), and output the base-10 logarithm of that quantity, along with the corresponding discrete time, $t^{n+1/2}$, to standard output. Specifically, assuming that the real*8 variable scnrm2rhat contains the scaled ℓ_2 norm of \hat{r} defined by (62)—where the discretization level, ℓ , is to be identified with the command-line argument, <lev>—and that the real*8 variables t and dt contain the discrete time, t^n , and time step, Δt , respectively, your program should include an output statement such as

write(*,*) t + 0.5d0 * dt, log10(scnrm2rhat)

Note that the standard output from invocations of diff2dadi with varying discretization levels can then be "overlaid" for comparison, with no further post-processing required, using, e.g., gnuplot or xvs.

In order to facilitate computation of the scaled independent residuals, your implementation of diff2dadi should make use of the instructor supplied routines for this problem that are defined in the source file \sim phys410/util/diff2dadi/diff2dadi_util.f. Specifically, you should copy this source file into your solution directory for this problem, and incorporate it into your executable. You should then ensure that the routine clcresidcn is called at each discrete time, $t^n, n = 0 \dots n_t - 1$. Note that clcresidcn has the header

```
subroutine clcresidcn(r,unp1,un,nx,ny,dx,dy,dt)
implicit none
integer nx, ny
real*8 r(nx,ny), unp1(nx,ny), un(nx,ny)
real*8 dx, dy, dt
```

so that, in particular, storage must be passed in for an entire grid function's worth of residuals, r(nx,ny). Given the array inputs unp1 and un—which contain $u_{i,j}^{n+1}$ and $u_{i,j}^{n}$, respectively—as well as the self-explanatory scalar inputs, nx, ny, dx, dy and dt, clcresidcn will compute the *unscaled* CN residuals as defined by (60), and return the values in the output array, r. Following the call to clcresidcn, the ℓ_2 norm of the residuals can be computed using the real*8 function dmnrm2

real*8 function	dmnrm2(a,m,n)
implicit	none
integer	m, n
real*8	a(m,n)

which is also defined in diff2dadi_util.f.

As in the previous problem, it is up to you to ensure that your implementation of diff2dadi is correct (i.e. convergent) using independent residual evaluation as described above, as well as the cvtestsdf utility, and, if necessary, other testing procedures of your own design.

Problem 3a) Once you are confident that your implementation of diff2dai is correct, execute the following sequence of commands in your solution directory

% diff2dadi 0.0625 6 6 0.05 > cn-res-6 % diff2dadi 0.0625 7 6 0.05 > cn-res-7 % diff2dadi 0.0625 8 6 0.05 > cn-res-8 % diff2dadi 0.0625 9 6 0.05 > cn-res-9 Note that this should generate .sdf files u_6.sdf, u_7.sdf, u_8.sdf and u_9.sdf, and should capture the standard output (discrete time and log₁₀ of the scaled independent residuals) of the invocations in the ASCII files cn-res-[6789]. Use gnuplot or another plotting package to make a postscript file named cnres6789.ps that shows the data from cn-res-[6789] on a *single* plot. Important: Ensure that you have used initial data of the form (59) for your final calculations and plot.